

matlab

벡터, 행렬 연산

$$\underline{a} \cdot b = a_1 b_1 + \dots \quad \vec{a} = (a_1, \dots, a_n)$$

$$a .* b = (a_1 b_1, a_2 b_2, \dots, a_n b_n)$$

$$a.^3 = (a_1^3, a_2^3, \dots, a_n^3)$$

$$\sin(a) = (\sin(a_1), \dots, \sin(a_n))$$

$$\int_0^1 \sin(x) dx = \text{sum} \left(\sin(x) \frac{1}{N} \right)$$

$$x = \left(0, \frac{1}{N}, \dots, \frac{N}{N} \right)$$

$$L = \frac{1}{2} (\partial_\mu \phi)^2 - \frac{1}{2} (\phi^2 - 1)^2$$

$$\partial_\mu^2 \phi = -2\phi(\phi^2 - 1)$$

$$\partial_t^2 \phi - \partial_x^2 \phi + 2(\phi^3 - \phi) = 0$$

$$\phi = \phi(x - vt)$$

$$\phi' (v^2 - 1) \phi'' + 2(\phi^3 - \phi) \phi' = 0$$

$$(v^2 - 1) \frac{1}{2} ((\phi')^2)' + \frac{1}{2} (\phi^4 - \phi^2)' = 0$$

$$(v^2 - 1) \phi'^2 + \phi^4 - \phi^2 = \text{const.}$$

$x \rightarrow \pm\infty, \phi' = 0, \phi = \pm 1$

$$1 - \phi^2 = 1 - \tanh^2 y = \frac{1}{\cosh^2 y}$$

$$\phi = \tanh y$$

$$d\phi = \frac{dy}{\cosh^2 y}$$

$$\downarrow \left(\frac{d\phi}{dx} \right)$$

$$= \frac{\phi \sqrt{1 - \phi^2}}{\sqrt{v^2 - 1}}$$

$$\rightarrow \int \frac{d\phi}{\phi \sqrt{1 - \phi^2}} = \int \frac{dx}{\sqrt{v^2 - 1}}$$

$$\int \frac{\tanh y / \cosh^2 y}{\tanh y / \cosh y} = \frac{x - x_0}{\sqrt{v^2 - 1}}$$

$$\frac{d\phi}{dx} = \sqrt{2U}$$

$$U = \frac{1}{4}(\phi^2 - 1)^2$$

$$\frac{1}{\phi-1} + \frac{1}{\phi+1} \int \frac{d\phi}{\phi^2-1} = \int dx = \frac{x-x_0}{\sqrt{2}}$$

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$$\frac{1}{2} \ln \frac{\phi-1}{\phi+1} \rightarrow \frac{\phi-1}{\phi+1} = e^{2\left(\frac{x-x_0}{\sqrt{2}}\right)}$$

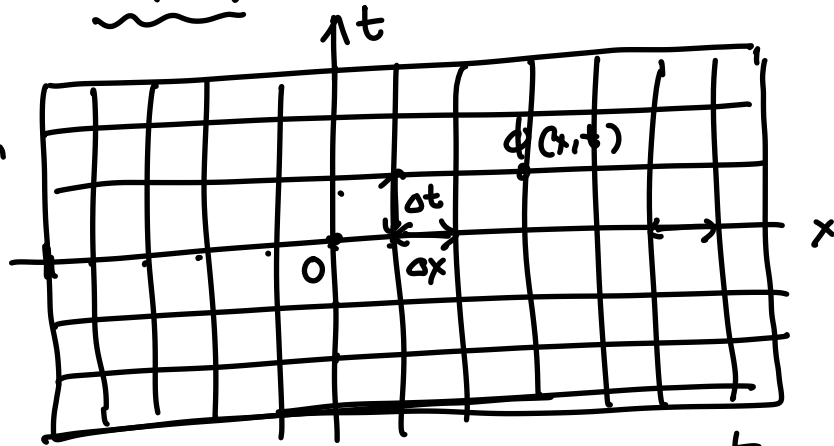
$$\phi = \frac{e + 1}{1 - e} = \pm \tanh\left(\frac{x-x_0}{\sqrt{2}}\right)$$

$$\rightarrow \boxed{\partial_t^2 \phi - \partial_x^2 \phi + \phi(\phi^2 - 1) = 0}$$

$$\phi(x, t) = \tanh\left(\frac{x - vt - x_0}{\sqrt{2}\sqrt{1-v^2}}\right)$$

$$\partial_t^2 \phi - \partial_x^2 \phi + \phi(\phi^2 - 1) = 0$$

discretize :



$$\Delta x, \Delta t \rightarrow 0$$

$$\phi(x, t) \rightarrow \phi_{i \leftarrow x}^n \leftarrow t$$

$$\partial_x \phi(x) =$$

$$\frac{\phi(x + \Delta x) - \phi(x)}{\Delta x}$$

$$= \frac{\phi_{i+1}^n - \phi_i^n}{\Delta x}$$

$$\partial_t \phi =$$

$$\frac{\phi_i^{n+1} - \phi_i^n}{\Delta t}$$

$$\partial_x^2 \phi = \frac{\phi'(x + \Delta x) - \phi'(x)}{\Delta x}$$

$$=$$

$$\frac{\left(\frac{\phi_{i+2}^n - \phi_{i+1}^n}{\Delta x} \right) - \left(\frac{\phi_{i+1}^n - \phi_i^n}{\Delta x} \right)}{\Delta x}$$

$$\frac{\phi_{i+2}^n + \phi_i^n - 2\phi_{i+1}^n}{\Delta x^2}$$

$$\partial_t^2 \phi \rightarrow$$

$$\frac{\phi_i^{n+2} + \phi_i^n - 2\phi_i^{n+1}}{(\Delta t)^2}$$

$$\partial_t^2 \phi - \partial_x^2 \phi + \phi^3 - \phi = 0$$

$$\frac{\phi_i^{n+1} + \phi_i^{n-1} - 2\phi_i^n}{\Delta t^2} - \frac{\phi_{i+1}^n + \phi_{i-1}^n - 2\phi_i^n}{\Delta x^2} + \phi_i^{n3} - \phi_i^n = 0$$

$$\phi_i^n \in 1, 2, 3, \dots$$

$$\phi_i^{n+1} = 2\phi_i^n - \phi_i^{n-1} + \frac{\Delta t^2}{\Delta x^2} (\phi_{i+1}^n + \phi_{i-1}^n - 2\phi_i^n) + (\phi_i^n - \phi_i^{n3}) \Delta t^2$$

초기조건

$$t=0 \rightarrow \left. \begin{aligned} \phi(x, t=0) &= \phi_i^1 \\ \dot{\phi}(x, t=0) &= \frac{\phi_i^2 - \phi_i^1}{\Delta t} \Rightarrow \phi_i^2 \end{aligned} \right\}$$

$$\begin{pmatrix} \vec{v} \end{pmatrix}_{i+1} = \begin{pmatrix} \vec{v} \end{pmatrix}_i$$

(ex)

$$\begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} \rightarrow \begin{pmatrix} v_2 \\ v_3 \\ v_1 \end{pmatrix}$$

$$\underbrace{\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}}_{L} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}$$

$$(L \cdot \vec{v})_i = \vec{v}_{i+1}$$

$$R = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} v_3 \\ v_1 \\ v_2 \end{pmatrix}$$

$$(R \cdot \vec{v})_i = \vec{v}_{i-1}$$

$$\phi_i^{n+1} = 2\phi_i^n - \phi_i^{n-1} + \frac{\Delta t^2}{\Delta x^2} \left(\phi_{i+1}^n + \phi_{i-1}^n - 2\phi_i^n \right) + \left(\phi_i^n - \phi_i^3 \right) \Delta t^2$$

$$\vec{\phi}^{(n+2)} = 2\vec{\phi}^{(n+1)} - \vec{\phi}^{(n)} + \frac{\Delta t^2}{\Delta x^2} \left(L \cdot \vec{\phi}^{(n+1)} + R \cdot \vec{\phi}^{(n)} - 2\vec{\phi}^{(n)} \right) + \left(\vec{\phi}^{(n+1)} - \vec{\phi}^{(n)3} \right) \Delta t^2$$
